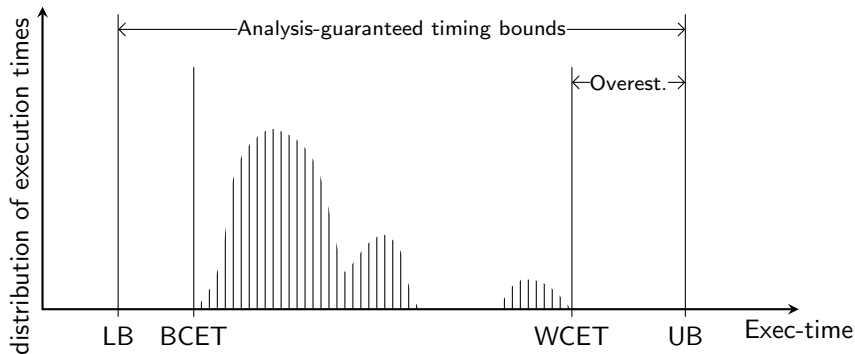


# W-SEPT ANR project (W-7): WCET and synchronous program

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Synchron 2012



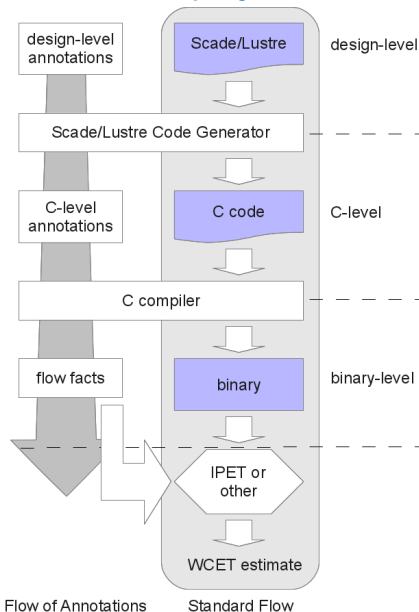


### WCET and semantics

- semantics influence the execution path

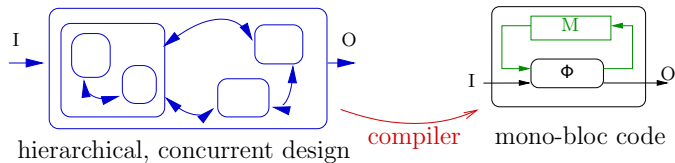
⇒ "feasible" worst-case path

# Structure du projet



## W-SEPT Partners:

- IRIT Toulouse
- Inria Rennes
- Continental Toulouse
- Verimag Grenoble (coordinator)



A basic compiler produces an "object-like" code:

- A (remanent) static memory (no DA).
- A step method: purely sequential code (static scheduling)  
mainly a sequence of assignment + conditional,  
maybe some loops, but statically bounded (e.g. arrays iter/fold)

Remark: providing such a compiler makes the source language a *de facto synchronous language* (e.g. c-code generators for Simulink/Stateflow)

## Basic mono-bloc

- Synchronous compilers produce the application software (the "object"). Implementation depends on a particular middleware/hardware
- Basically, a synchronous code can run "bare metal" (some drivers for input/output, but no complex OS like dynamic scheduler)
- e.g. a simple periodic implementation (period comes from a specialist of the domain):

```
var I, O, M
M := M0
each period do
  read(I)
  O, M = step(I, M)
  write(O)
end
```

- Computes an upper *bound* of the WCET of the step method (+ necessary I/O latency)
- check that  $bound < period$
- If yes: the system does not miss any change from the environment,  
the synchronous hypothesis is valid

## Open questions

- SP helps TA (at least) because:
  - ▶ it guarantees that WCET exists
  - ▶ it makes the analysis simpler : almost heap-free code, no aliasing problems
- Could it be better ?
  - ▶ Discovering (non-trivial) infeasible path ?

- A path is semantically impossible because the corresponding **conjunction of conditions is always false**, for any execution of the program.

⇒ How to make these conditions explicit ?

Find relations between them ?

Check satisfiability ?

- ▶ At binary level/C level: not obvious, require to build some "propositional" representation of the program (e.g. SSA form)
- ▶ At the Lustre level: much more convenient, already in some "clean mathematical" form, moreover verification tools are available.



## The "theorem"

For **any branch in the binary code**, there must exist a **Boolean expression in the source code** whose value coincide to the predicate "the branch is taken".

Proof: otherwise the compiler is certainly buggy!

Problem: OK, but how to find these expressions?

- requires a traceability between binary and C code, C code and Lustre,
- between Lustre and C: not a big problem, the compiler is under control...
- much more tricky between C and binary (e.g. strongly depends on optimisations)
- The problem has to be investigated ...
- ... Let's try with a simple case.

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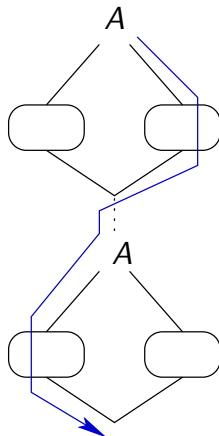
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Simple compilation scheme:

- **Lustre**  $\rightarrow$  **C** compiler adapted in such a way that all conditional are of the form `if (E) ...`, where **E** coincide with a Lustre expression.
- **C compiler** is called in "debug" mode (no optimization), in such a way that all branching instruction is flagged by the corresponding `if (E) ...`
- A path in the binary code corresponds to a conjunction of literals (e.g.  $E1 \wedge E2 \wedge \neg E3$ )
- A decision tool is used to check if the conjunction (the path) is satisfiable (feasible)

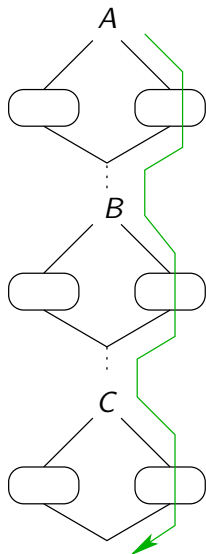
## Structural/syntactical

- based on identity
- decision procedure unnecessary
- could have been done at binary level (maybe via SSA reconstruction)



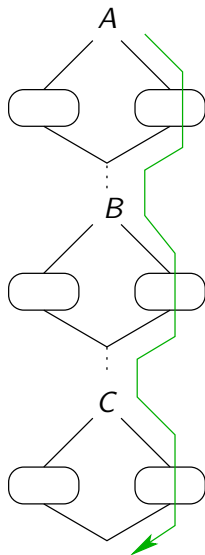
## Due to statical unsatisfiability

- Examples:
  - ▶  $A = E, B = \text{not } E,$
  - ▶  $A = x \text{ xor } y, B = y \text{ and } z,$   
 $C = x \text{ and } t$
  - ▶  $A = x + y > 10, B = y \leq 2,$   
 $C = 2 * x < 15$
- requires decision procedure, e.g. Sat (Modulo Theory) solver
- could have been done at binary level (maybe via SSA reconstruction)



## Due to dynamic unreachability

- $A = \text{if } PA \text{ then not } x \text{ else } (PC \text{ and } x);$   
 $B = PB \text{ and not } y \text{ or } PA \text{ and } x \text{ or } PC \text{ and not } x \text{ and } y;$   
 $C = PC \text{ and not } (y \text{ or } x) \text{ or } PC \text{ and } y;$
- where  $PA, PB, PC$  are the values of  $A, B, C$  computed at the previous cycle
- (almost) impossible to discover at C/binary level
- strongly depends on the "dynamic" nature of the program
- requires reachability (model-checking) techniques





## Semantic "facts"

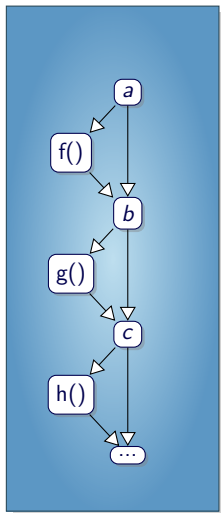
- simple ones can be expressed/discovered more easily at the Lustre level ...
- ... as far as we are able to relate binary branches to Lustre expressions !
- complex (dynamic) ones are very hard (impossible) to handle at binary level

## Traceability

- dramatically depends on the C compiler
- how to deal with optimisation?

## Complexity/Strategy

- checking feasibility can be extremely expensive
- require strategy/heuristics:
  - ▶ limitation to pair-wise relations between conditions
  - ▶ check satisfiability afterwards (to refute the WCET estimation), or first (to simplify the WCET estimation problem)
- simple pair-wise relations can be expressed in ILP (implications)
- open problem: is it the best method ?



OTAWA: WCET= 3000 cycles

MiniTool: worst-case path in Lustre  
a and b and c

Lesar: path is not possible !

lp:  $x_f + x_g \leq 1$

$$x_f + x_h \leq 1$$

$$x_g + x_h \leq 1$$

lpsolve: WCET= 2500 cycles

Lustre compiler: variableC

⇒ ExprLustre

C compiler: testC=f(variableC)

⇒ @ instruction

OTAWA: @ instruction ⇒ CFG basic block

⇒ worst-case path

MiniTool : worst-case path

⇒ property = conjunction of ExprLustre

Lesar: property

⇒ feasible path?

- Traceability from Lustre to C:
  - ▶ from C to binary?
  - ▶ from Scade to C?
- No loop in our model:
  - ▶ only loop bounds?
  - ▶ need of loop-iteration identifier?
- Compiler optimization:
  - ▶ from not-optimized to fully optimized?
  - ▶ from precise estimation of WCET to better code?